



Faculty of Science



Post-selection inference: risk estimation after data-driven model selection

Code for simulations

Niels Richard Hansen, Frederik Riis Mikkelsen &
Alexander Sokol
Department of Mathematical Sciences



AIC for Gaussian regression (fixed variance)

If $Y \sim \mathcal{N}(\xi, \sigma^2 I)$ then

$$\text{AIC} = \|Y - \hat{\xi}\|^2 / \sigma^2 + 2d$$

when σ^2 is fixed and $\hat{\xi}$ is the least squares estimator in a subset of dimension d .

Fix $\sigma^2 = 1$ from hereon, and for $\lambda \in \Lambda$ (an index set) let

$$\text{AIC}(\lambda) = \|Y - \hat{\xi}^\lambda\|^2 + 2d(\lambda).$$

Example: $\xi = X\beta$ for X and $n \times p$ matrix and $\beta \in \mathbb{R}^p$.



AIC as a test error and risk estimate

Let $Y \perp\!\!\!\perp Y^{\text{New}}$ and $Y \stackrel{\mathcal{D}}{=} Y^{\text{New}}$.

If $Y \sim (\xi, I)$, $\hat{\xi}^\lambda = S_\lambda Y$ and $d(\lambda) = \text{tr}(S_\lambda)$ then

$$E(\text{AIC}(\lambda)) = E\|Y^{\text{New}} - \hat{\xi}^\lambda\|^2 = n + \underbrace{E\|\xi - \hat{\xi}^\lambda\|^2}_{\text{MSE}}.$$

Thus

$$\text{AIC}(\lambda) - n = \|Y - S_\lambda Y\|^2 + 2d(\lambda) - n$$

is an unbiased estimate of MSE.



Forward stepwise variable selection

If S_λ is a **fixed** projection then $d(\lambda) = \text{rank}(S_\lambda)$.

Forward stepwise variable selection results in a sequence of projections

$$S_0, \dots, S_p$$

onto nested subspaces of dimensions $0 < 1 < 2 \dots < p$.

Note: S_d is **selected in a data dependent way**.



Model weights and model averaging

Introduce weights

$$w_{\gamma}(\lambda) = \frac{\exp(-\gamma \text{IC}(\lambda))}{\int \exp(-\gamma \text{IC}(\lambda)) \pi(d\lambda)}.$$

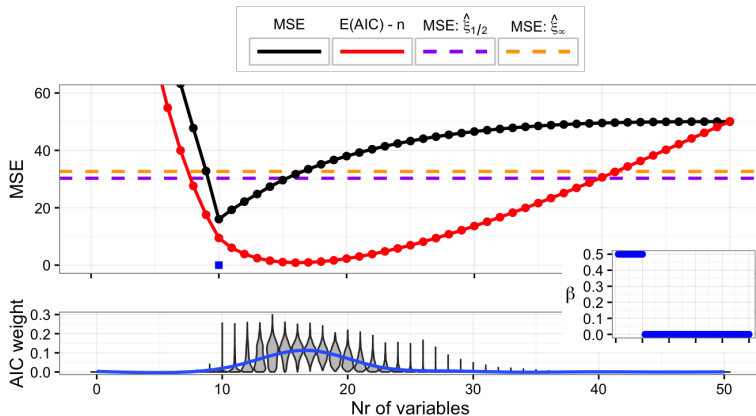
- $\gamma = 1/2$ has a Bayes interpretation
- $\gamma \rightarrow 0$ gives all models the same weight
- $\gamma \rightarrow \infty$ concentrates the weights on models with minimal IC.

$$\hat{\xi}_{\gamma} = \int \hat{\xi}(\lambda) w_{\gamma}(\lambda) \pi(d\lambda)$$

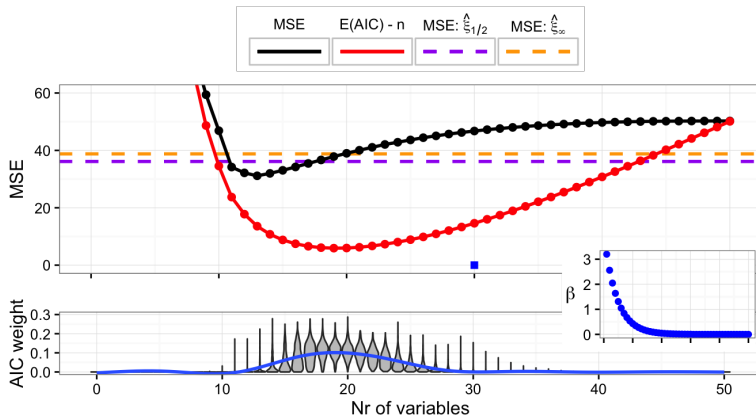
is the model averaging estimator.



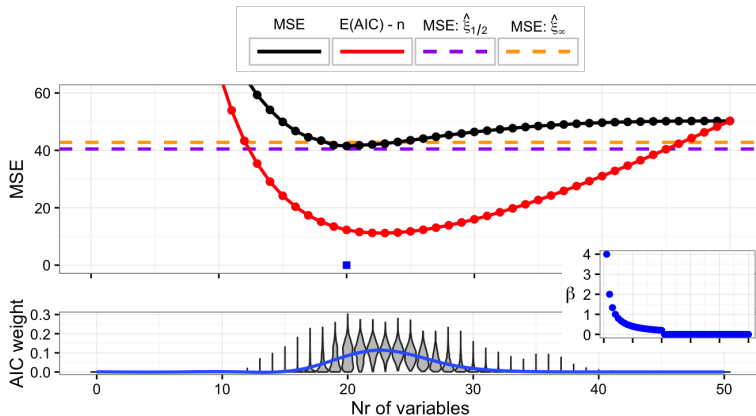
$$n = 100, p = 50$$



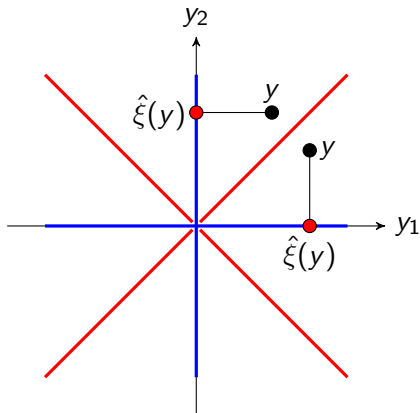
$$n = 100, p = 50$$



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Best subspace selection



Best subspace selection is the projection onto the union of subspaces. The estimator is **discontinuous** on the union of the diagonals.



Fundamental identity

Recall the fundamental AIC identity

$$\underbrace{E\|Y^{\text{New}} - \hat{\xi}\|^2}_{\text{expected test error}} = \underbrace{E\|Y - \hat{\xi}\|^2}_{\text{expected training error}} + 2d,$$

which justifies

$$\text{AIC} = \|Y - \hat{\xi}\|^2 + 2d$$

as a prediction error estimate and $\text{AIC} - n$ as a risk estimate.

For **Lipschitz continuous estimators** (Stein's lemma)

$$d = E(\nabla \cdot \hat{\xi}).$$

Theorem (NRH, Mikkelsen, Sokol)

In general

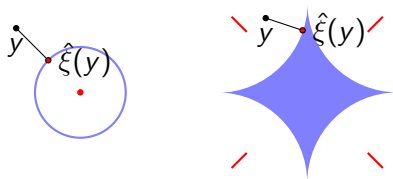
$$d = E(\nabla \cdot \hat{\xi}) + \frac{1}{(2\pi)^{n/2}} \int e^{-\frac{\|y - \xi\|^2}{2}} d\nu(dy)$$

with ν a measure singular w.r.t. Lebesgue measure.



The singular measure ν

\mathcal{H}^{n-1} is Hausdorff measure.



- If $E \subseteq \mathbb{R}^n$ is closed and $\hat{\xi} : E^c \rightarrow \mathbb{R}^n$ is **continuously differentiable** then $\nu = 0$ if $\mathcal{H}^{n-1}(E) = 0$. (Reduced rank estimators, NRH (2018) *Stat. Prob. Letters*.)
- If $\hat{\xi}$ is a **metric projection** onto a closed subset of \mathbb{R}^n then ν is a **positive** measure (NRH & Sokol, arXiv:1402.2997).
- If $\hat{\xi} = \sum_i \hat{\xi}^i 1_{U_i}$ then

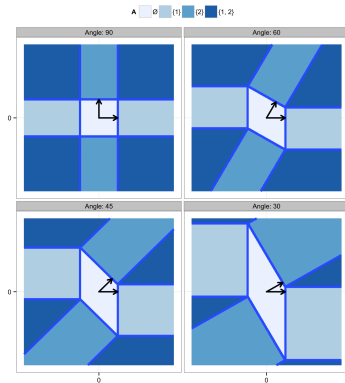
$$\nu = \frac{1}{2} \sum_{i \neq j} 1_{\overline{U_i} \cap \overline{U_j}} \langle \hat{\xi}^j - \hat{\xi}^i, \eta_i \rangle \cdot \mathcal{H}^{n-1}$$

with η_i the outer unit normal to the boundary of U_i .
(Mikkelsen & NRH (2018), *Ann. Inst. H. Poincaré Probab. Statist.*)

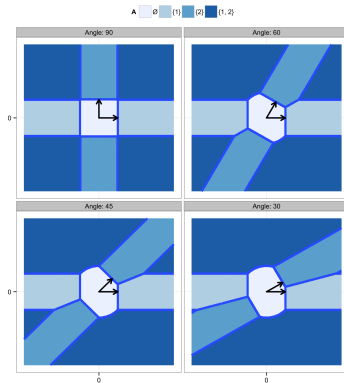


Two examples

Lasso-OLS



Best subset selection



<http://web.math.ku.dk/~richard/selectionAnimation.html>



The correction term

Suppose that $U_i^t = F(t, U_i^0)$ and $\hat{\xi}^{i,t}$ are parametrized by $t \in \mathbb{R}$ and F is a **flow**.

Example: Lasso gives $U_i^t = e^t U_i^0$ for penalty $\lambda = e^t$.

Theorem (Mikkelsen & NRH, in preparation)

There is a statistic $H(t, Y)$ such that under technical conditions

$$\frac{1}{(2\pi)^{n/2}} \int e^{-\frac{\|y - \xi\|^2}{2}} d\nu^t(dy) = \partial_t E(H(t, Y)).$$

Example: Lasso-OLS gives $H(t, Y) = -\nabla \cdot \hat{\xi}^t(Y)$.

Applies to: marginal screening, relaxed lasso, best subset selection, some smoothing-selection algorithms and greedy basis pursuit.



A refined information criterion

We propose

$$\text{IC}(t) = \|Y - \hat{\xi}^t(Y)\|^2 + 2 \left(\nabla \cdot \hat{\xi}^t(Y) + \partial_t \text{smooth}(H(t, Y)) \right)$$

with $\text{smooth}(H(t, Y))$ denoting a t -smoothing of the stochastic jump function $t \mapsto H(t, Y)$.

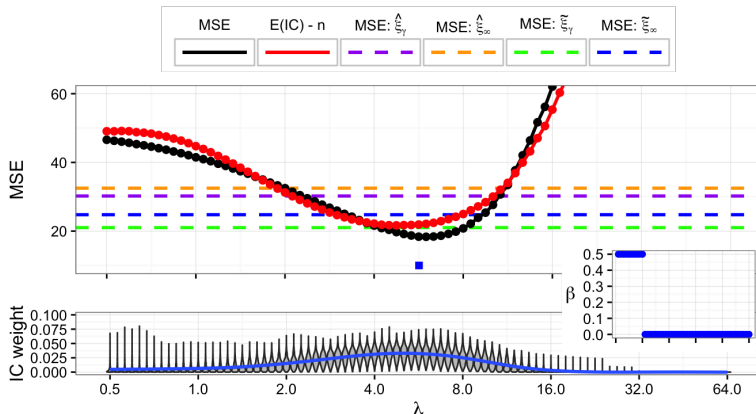
Forward stepwise variable selection can be recast in flow-form as

$$d(t) = \arg \min_{d=0, \dots, p} \|Y - S_d Y\|^2 + \underbrace{e^{2t}}_{\lambda} d$$

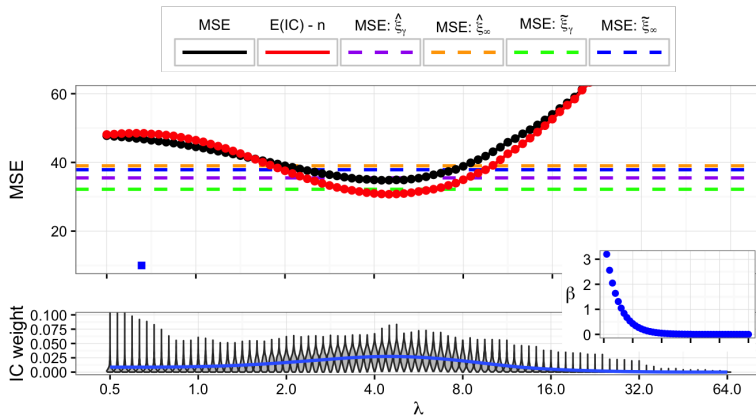
with $\nabla \cdot \hat{\xi}^t(Y) = d(t)$.



$$n = 100, p = 50, \gamma = 0.1$$



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